## C1115.002.000 - Motion Controller

## Overview

The Optec Motion Controller controls two different DC motors at the same time with a maximum output current of 4 A (2 A for each motor). It implements a complete PID position control system with continuous movement on the entire working range and with preset fixed positions.

To communicate with the PC the Optec Motion Controller uses the standard serial protocol RS232 thru USB or Serial DB9 connector.

| Absolute Maximum ratings |  |
| :--- | :---: |
| Maximum DC output <br> current | 2 A (for each motor) |
| Maximum peak <br> output current | 3 A (for each motor) |
| Maximum Supply <br> voltage | 20 V |
| Input analog voltage | 5 V |
| Temperature working <br> range | -10 to $70^{\circ} \mathrm{C}$ |


| Size |  |
| :--- | :--- |
| Weight | 125 g |
| Length | 77 mm |
| Depth | 60 mm |
| Height | 34 mm |
| Maximum height (with <br> connector) | 40 mm |

## USB overcurrent protection

The Optec Motion Controller has a resettable polyfuse that protects the computer's USB ports from short-circuits and overcurrents. If more than 500 mA is applied to the USB port, the fuse will automatically break the connection until the short or overload is removed.

| Electronic features |  |  |  |
| :---: | :---: | :---: | :---: |
| Input voltage supply | 12 V (from external power pack) | Output voltage (to potentiometers) | 0 to 5 V |
| Number of independent channels | 2 | Minimum current consumption | 30 mA |
| Number of analog inputs | 2 | Maximum current consumption (without motors) | 40 mA |
| Analog input voltage | 0 to 5 V | Analog input sampling rate | 10.6 Mhz |
| Output voltage (to motors) | 0 to 9.79 V (in both directions) | Clock speed | 16 MHz |


| Serial Interface |  |  |  |
| :---: | :---: | :---: | :---: |
| Serial protocol | RS232 (8-N-1) | Data bits | 8 |
| Serial port <br> connector | Standard DE-9 | Parity | None |
| Baud rate | 9600 bps | Stop bit | 1 |

## Connector pin list

$1-+5 \mathrm{~V}$
2 - GND
3 - Analog input 1
4 - Analog input 2
5 - Reserved
6 - Reserved
7 - Motor 1 +
8 - Motor 1 -
9 - Motor 2 +
10 - Motor 2 -

